Dijkstra's Algorithm

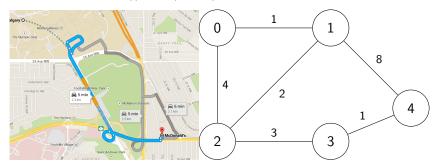
Problem Solving Club

February 1, 2017

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Dijkstra's algorithm

- Dijkstra's is a greedy algorithm that finds shortest paths from a single source to every other vertex in the graph.
- As usually implemented:
 - Works for weighted graphs with non-negative weights.
 - Works for **directed** and **undirected** graphs.
 - Runs in $O((V + E) \log V)$.



Binary heap (priority queue) data structure

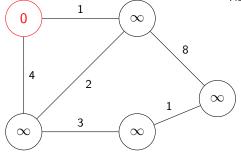
- A binary heap is a data structure with two operations:
 - **Insert:** Insert an element into the heap.
 - **Extract:** Remove the max (or min) element from the heap.

- Both operations take at worst $O(\log N)$.
- ► C++ std::priority_queue, Java PriorityQueue

Dijkstra's Algorithm

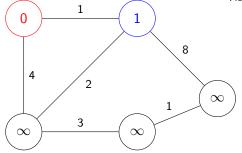
Procedure:

- 1. Assign all nodes a (tentative) distance of infinity.
- 2. Mark all nodes as unvisited.
- 3. Set the current node as start point and set its distance to zero.
- For the current node, consider all neighbours. If [distance to current node + edge weight] is smaller than the current tentative distance of that node, update its tentative distance.
- 5. Mark the current node as visited.
- 6. Set the current node to the unvisited node with the smallest tentative distance, and go back to step 4 until there are no more unvisited nodes.



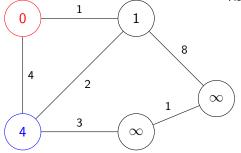
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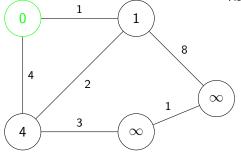
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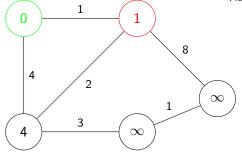
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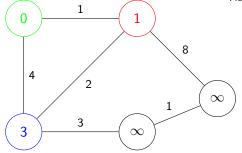
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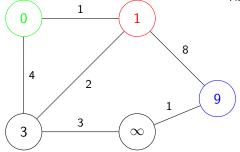
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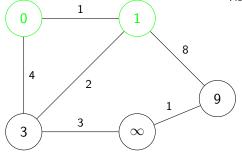
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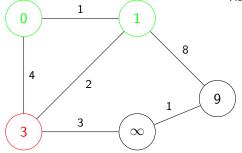
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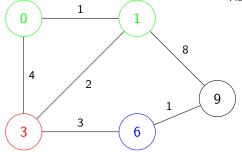
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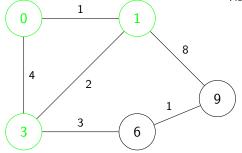
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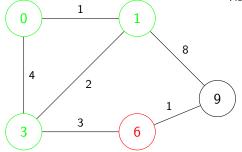
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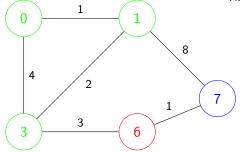
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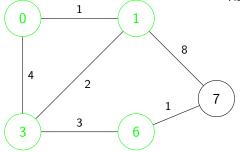
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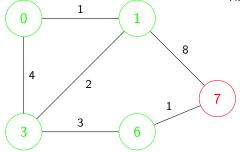
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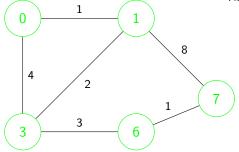
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Example code

```
vector <edge> adj[100];
vector <int > dist(100, INF);
void dijkstra(int start) {
    dist[start] = 0;
    priority_queue <pair <int, int>,
                    vector<pair<int, int> >,
                    greater<pair<int, int> > > pq;
    pg.push(make_pair(dist[start], start));
    while (!pq.empty()) {
        int u = pq.top().second,
            d = pq.top().first;
        pg.pop():
        if (d > dist[u]) continue;
        for (int i = 0; i < adj[u].size(); i++) {</pre>
            int v = adj[u][i].v,
                 w = adj[u][i].weight;
            if (w + dist[u] < dist[v]) {</pre>
                 dist[v] = w + dist[u]:
                 pq.push(make_pair(dist[v], v));
             }
       }
    }
3
```

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Frequently asked questions

- How do I find the actual shortest paths?
 - Keep track of each vertex's parent using a separate array.
- Can I use std::set or TreeSet instead of a binary heap?
 - Yes. Same asymptotic performance, but worse in practice.
- Can Dijkstra's find the longest path in a graph?
 - ▶ No. Longest path problem for general graph is NP-hard.
- What if my graph has negative weights?
 - Bellman-Ford / Shortest Path Faster Algorithm: O(VE).
 - Same as Dijkstra's, but works with negative weights/cycles.
 - Floyd-Warshall: $O(V^3)$.
 - Finds the shortest path between every pair of vertices.
 - These have much worse running time than $O((V + E) \log V)$.